

VE.Direct protocol

Rev 5

www.victronenergy.com

VE.Direct Protocol

Phoenix Inverters



Table of Contents

| 1 VE | E.Direct Protocol | 3 |
|---------|----------------------------------|----|
| 1.1 | VE.Direct commands | 3 |
| 1.2 | Product ID values | 5 |
| 1.3 | Message examples | 7 |
| 1.4 | Text Protocol | 7 |
| 2 In | verter register description | 8 |
| 2.1 | Saving and Reverting registers | 8 |
| 2.2 | Product information registers | 9 |
| 2.3 | Generic device status registers | 10 |
| 2.4 | Generic device control registers | 12 |
| 2.5 | Inverter operation registers | 13 |
| 2.6 | User AC-out control registers | 13 |
| 2.7 | User battery control registers | 15 |
| 2.8 | Relay control registers | 16 |
| Revisio | on Log | |



1 VE.Direct Protocol

1.1 VE.Direct commands

The frame format of the VE.Direct protocol has the following general format:

: [command] [data][data][...] [check]\n

Where the colon indicates the start of the frame and the newline is the end of frame. The sum of all data bytes and the check must equal 0x55. Since the normal protocol is in text values the frames are sent in their hexadecimal ASCII representation, ['0' .. '9'], ['A' .. 'F'], must be uppercase. There is no need to escape any characters.

: [command] [dataHighNibble, dataLowNibble][.....] [checkHigh, checkLow] \n

Note: The command is only sent as a single nibble. Numbers are sent in Little Endian format. An error response with value 0xAAAA is sent on framing errors.

| Command | | Description | | |
|--------------|----------------|--|--|--|
| 0 | Enter boot | 0x51FA51FA51FA51FA51FA as payload will enable bootloader mode. | | |
| 1 | Ping | Check for presence, the response is an 'Rsp ping' containing version and firmware type. See the response ping message. | | |
| 3 | App version | Returns the version of the firmware as stored in the header in an 'Rsp Done' message. | | |
| 4 | Product Id | Returns the Product Id of the firmware as stored in the header in an 'Rsp Done' message. | | |
| 6 | Restart | Restarts the device, no response is sent. | | |
| 7 | Get | Returns a get response with the requested data or error is returned. uint16 the id of the value to get uint8 flags, should be set to zero | | |
| 8 | Set | Returns a set response with the requested data or error is returned. uint16 the id of the value to set uint8 flags, should be set to zero type depends on id value | | |
| А | Async | Asynchronous data message. Should not be replied. uint16 the id of the value being returned uint8 flags, defined below type depends on id value | | |
| 2, 5, 9, B-F | reserved | | | |

VE.Direct_responses are formatted in the same manner as commands, but use response codes.:

| Response | | Description | | | |
|----------|---------|---|--|--|--|
| 1 | Done | Successful execution of the received command. Payload depends on command. | | | |
| 3 | Unknown | Unknown command, data is the unknown command. | | | |
| 4 | Error | Frame error (payload=0xAAAA), unable to enter bootloader (payload=0). | | | |
| 5 | Ping | The version number is directly interpreted from the hex representation, e.g. 0x0101 is version 1.01. The two most significant bits indicate the firmware type: b00: bootloader b01: application b10: tester b11: release candidate In case of release candidate the lowest two bits of the highest nibble together with type indicate the release candidate number. E.g. 0xD101 represents release candidate D of version 1.01. Note that there can only be 4 release candidates per version. | | | |
| 7 | Get | uint16 uint8 | id: of the value being returned flags: defined below | | |
| | | type depends on id | value | | |
| | | uint16 | id of the value which was set | | |
| 8 | Set | uint8 | flags: defined below | | |
| | | type depends on id | value | | |

The following set / get flags are currently defined (reply):

| Flag | Name | Meaning |
|------|-----------------|---|
| 0x01 | Unknown Id | The specified id does not exist |
| 0x02 | Not supported | Attempting to write to a read only value |
| 0x04 | Parameter Error | The new value is out of range or inconsistent |

1.2 Product ID values

The product ID (PID) defines whether firmware is compatible with the device. Next a list of all VE.Direct and Smart inverters who support the VE.Direct Protocol as described in this document.

| Device | Name | Remark |
|-------------|--|-----------------------------------|
| A201 | Phoenix Inverter 12V 250VA 230Vac | obsolete (32k) |
| A202 | Phoenix Inverter 24V 250VA 230Vac | obsolete (32k) |
| A204 | Phoenix Inverter 48V 250VA 230Vac | obsolete (32k) |
| A211 | Phoenix Inverter 12V 375VA 230Vac | obsolete (32k) |
| A212 | Phoenix Inverter 24V 375VA 230Vac | obsolete (32k) |
| A214 | Phoenix Inverter 48V 375VA 230Vac | obsolete (32k) |
| A221 | Phoenix Inverter 12V 500VA 230Vac | obsolete (32k) |
| A222 | Phoenix Inverter 24V 500VA 230Vac | obsolete (32k) |
| A224 | Phoenix Inverter 48V 500VA 230Vac | obsolete (32k) |
| A231 | Phoenix Inverter 12V 250VA 230Vac 64k | |
| A232 | Phoenix Inverter 24V 250VA 230Vac 64k | |
| A234 | Phoenix Inverter 48V 250VA 230Vac 64k | |
| A239 | Phoenix Inverter 12V 250VA 120Vac 64k | |
| A23A | Phoenix Inverter 24V 250VA 120Vac 64k | |
| A23C | Phoenix Inverter 48V 250VA 120Vac 64k | |
| A241 | Phoenix Inverter 12V 375VA 230Vac 64k | |
| A242 | Phoenix Inverter 24V 375VA 230Vac 64k | |
| A244 | Phoenix Inverter 48V 375VA 230Vac 64k | |
| A249 | Phoenix Inverter 12V 375VA 120Vac 64k | |
| A24A | Phoenix Inverter 24V 375VA 120Vac 64k | |
| A24C | Phoenix Inverter 48V 375VA 120Vac 64k | |
| A251 | Phoenix Inverter 12V 500VA 230Vac 64k | |
| A252 | Phoenix Inverter 24V 500VA 230Vac 64k | |
| A254 | Phoenix Inverter 48V 500VA 230Vac 64k | |
| A259 | Phoenix Inverter 12V 500VA 120Vac 64k | |
| A25A | Phoenix Inverter 24V 500VA 120Vac 64k | |
| A25C | Phoenix Inverter 48V 500VA 120Vac 64k | |
| A261 | Phoenix Inverter 12V 800VA 230Vac 64k | |
| A262 | Phoenix Inverter 24V 800VA 230Vac 64k | |
| A264 | Phoenix Inverter 48V 800VA 230Vac 64k | |
| A269 | Phoenix Inverter 12V 800VA 120Vac 64k | |
| A26A | Phoenix Inverter 24V 800VA 120Vac 64k | |
| A26C | Phoenix Inverter 48V 800VA 120Vac 64k | |
| A271 | Phoenix Inverter 12V 1200VA 230Vac 64k | |
| A272 | Phoenix Inverter 24V 1200VA 230Vac 64k | |
| A274 | Phoenix Inverter 48V 1200VA 230Vac 64k | |
| A279 | Phoenix Inverter 12V 1200VA 120Vac 64k | |
| A27A | Phoenix Inverter 24V 1200VA 120Vac 64k | |
| A27C | Phoenix Inverter 48V 1200VA 120Vac 64k | Consent into queta al Divista ath |
| A281 | Phoenix Inverter Smart 12V 1600VA 230Vac 64k | Smart, integrated Bluetooth |
| A282 | Phoenix Inverter Smart 24V 1600VA 230Vac 64k | Smart, integrated Bluetooth |
| A284 | Phoenix Inverter Smart 48V 1600VA 230Vac 64k | Smart, integrated Bluetooth |
| A291 | Phoenix Inverter Smart 12V 2000VA 230Vac 64k | Smart, integrated Bluetooth |
| A292 | Phoenix Inverter Smart 24V 2000VA 230Vac 64k | Smart, integrated Bluetooth |
| A294 | Phoenix Inverter Smart 48V 2000VA 230Vac 64k | Smart, integrated Bluetooth |

| Device | Name | Remark |
|-------------|--|-----------------------------|
| A2A1 | Phoenix Inverter Smart 12V 3000VA 230Vac 64k | Smart, integrated Bluetooth |
| A2A2 | Phoenix Inverter Smart 24V 3000VA 230Vac 64k | Smart, integrated Bluetooth |
| A2A4 | Phoenix Inverter Smart 48V 3000VA 230Vac 64k | Smart, integrated Bluetooth |
| A2B1 | Phoenix Inverter Smart 12V 5000VA 230Vac 64k | Smart, integrated Bluetooth |
| A2B2 | Phoenix Inverter Smart 24V 5000VA 230Vac 64k | Smart, integrated Bluetooth |
| A2B4 | Phoenix Inverter Smart 48V 5000VA 230Vac 64k | Smart, integrated Bluetooth |
| A2E1 | Phoenix Inverter 12V 800VA 230Vac 64k HS | redesign (replaces A261) |
| A2E2 | Phoenix Inverter 24V 800VA 230Vac 64k HS | redesign (replaces A262) |
| A2E4 | Phoenix Inverter 48V 800VA 230Vac 64k HS | redesign (replaces A264) |
| A2E9 | Phoenix Inverter 12V 800VA 120Vac 64k HS | redesign (replaces A269) |
| A2EA | Phoenix Inverter 24V 800VA 120Vac 64k HS | redesign (replaces A26A) |
| A2EC | Phoenix Inverter 48V 800VA 120Vac 64k HS | redesign (replaces A26C) |
| A2F1 | Phoenix Inverter 12V 1200VA 230Vac 64k HS | redesign (replaces A271) |
| A2F2 | Phoenix Inverter 24V 1200VA 230Vac 64k HS | redesign (replaces A272) |
| A2F4 | Phoenix Inverter 48V 1200VA 230Vac 64k HS | redesign (replaces A274) |
| A2F9 | Phoenix Inverter 12V 1200VA 120Vac 64k HS | redesign (replaces A279) |
| A2FA | Phoenix Inverter 24V 1200VA 120Vac 64k HS | redesign (replaces A27A) |
| A2FC | Phoenix Inverter 48V 1200VA 120Vac 64k HS | redesign (replaces A27C) |

1.3 Message examples

\n at the end of the message is implied.

Ping

:154

:51641F9

0x4116 = talking to application version 1.16

Application version

:352

:11641FD

Like ping, application version 1.16

Product Id

:**45**1

:1000351

0x300 = BlueSolar MPPT 70|15

Restart

:64F

No response, restarted

Get Battery Maximum Current

:7F0ED0071

:7F0ED009600DB

Value = 0x0096 = 15.0A

Set Battery Maximum Current

Set to 10.0A = 0x0064

:8F0ED0064000C

:8F0ED0064000C

Acknowledged with the new value returned.

Unsupported command

253

:3020050

Unknown response

Invalid frame (checksum wrong)

:452

:4AAAAFD

Error response

Asynchronous message

:A0102000543

The unit reports register 0x0201 (device state) with value 0x05 (float).

1.4 Text Protocol

When no VE.Direct queries are sent to the device, the charger periodically sends human readable (TEXT) data to the serial port. See the "VE.Direct Protocol" document for a detailed description of the contents and availability of the information.

2 Inverter register description

The register in this chapter can be accessed for reading and/or writing by using the :**Get** (read) and :**Set** (write) commands of the VE.Direct Protocol. Whether the connection is established by using the actual VE.Direct-USB cable, or via a Bluetooth Dongle makes no difference.

2.1 Saving and Reverting registers

Registers used for user settings, need to be saved to none-volatile-memory (NVM) when modified. Unlike for most Victron products a register with a changed setting is **not automatically saved**

After changing one or more settings it is required to execute the NvmSave command via 0xEB99. Until this command is executed the registers will revert to the old (last saved) value after a power down cycle or reset.

| ID | Register name | R/W | Туре | Scale | Unit | Note |
|--------|------------------------|-----|------|-------|------|------|
| 0xEB99 | VE_REG_INV_NVM_COMMAND | W | un8 | | | |
| 0x0004 | VE_REG_RESTORE_DEFAULT | W | - | | | |

2.1.1 None-volatile memory command (register 0xEB99)

| Data | Command name | Description |
|------|--------------|---|
| 0 | No command | return value |
| 1 | NvmSave | Save current user settings to NVM |
| 2 | NvmRevert | Cancel modified settings. Load most recent saved user settings. |
| 3 | NvmBackup | Undo last save. Load second last time saved settings. After an update of the FW it is possible the backup is not available. Then the settings are reverted instead. |
| 4 | NvmDefault | Load the factory default values. Identical to VE_REG_RESTORE_DEFAULT 0x0004 |

2.1.2 Restore user defaults (register 0x0004)

When a write message is addressed to register Id 0x0004 all user settings of the device are restored to the factory default values. Factory calibration data is preserved. The data part of this message is not required and ignored.

2.2 Product information registers

Read only registers with static information about the device

| ID | Register name | R/W | Type | Scale | Unit | Note |
|--------|--|-------|--------|-------|------|------|
| 0x0100 | VE_REG_PRODUCT_ID | R | un32 | - | - | |
| 0x0101 | VE_REG_PRODUCT_REVISION Hardware version | R | un24 | - | - | |
| 0x0102 | VE_REG_APP_VER Software version | R | un32 | - | - | |
| 0x010A | VE_REG_SERIAL_NUMBER | R | string | - | - | |
| 0x010B | VE_REG_MODEL_NAME | R | string | - | - | |
| 0x2203 | VE_REG_AC_OUT_RATED_POWER | R | sn16 | 1 | VA | 1) |
| 0x0140 | VE_REG_CAPABILITIES1 | R | un32 | - | - | 2) |
| 0x0150 | VE_REG_CAPABILITIES_BLE | R/(W) | un32 | - | | 3) |
| 0x2202 | VE_REG_AC_OUT_NOM_VOLTAGE | R | un8 | 1 | V | 1) |
| 0xEDEF | VE_REG_BAT_VOLTAGE | R | un8 | 1 | V | 1) |

Note 1) Available since version 1.10

Note 2) Available since version 1.15

Note 3) Available since version 1.17 for Smart inverters only

2.2.1 Product ID (register 0x0100)

| Struct | Description |
|--------|-------------------------------|
| un8 | 0 |
| un16 | ID number of the device (PID) |
| un8 | 0xFE |

2.2.2 Product Revision (register 0x0101)

| Struct | Description |
|--------|--------------------|
| un8 | 0 |
| un16 | HW revision number |

2.2.3 FW application version (register 0x0102)

| Byte | Description |
|------|--|
| 0 | 0 |
| 1 | Minor |
| 2 | Major, + bits 7 and 6 indicate SW type: 00=bootloader 01=application (released) 02=tester 03=release candidate(beta) |

2.2.4 Capabilities (register 0x0140)

| Bit | Description of the option bit | Small 32k note1) | Small 64k <= 1200VA | Smart |
|-----|---|------------------------|---------------------------------------|-------------------|
| 8 | Remote input available | 1 | 1 | 1 |
| 17 | Built in user-relay available and support of registers: VE_REG_RELAY_MODE and VE_REG_RELAY_CONTROL | 0 | 0 | 1 |
| 27 | OpenPaygo token compatible | 0 | version >=1.17 | version >=1.17 |
| 28 | Support of device hibernation: VE_REG_DEVICE_MODE = VE_REG_MODE_HIBERNATE (0xFD) | 0 | 0 | 1 |
| 29 | Improved load current measurement and support of registers: VE_REG_AC_OUT_APPARENT_POWER and VE_REG_AC_LOAD_SENSE_POWER_THRESHOLD VE_REG_AC_LOAD_SENSE_POWER_CLEAR | 0 | revision >= 7, see register 0x0101 | 1 |

Note 1) Small 32k devices (PID A20x, A21x or A22x) are obsolete, production stopped in November 2016

2.2.5 Capabilities BLE (register 0x0160)

| Bit | Description of the option bit |
|-----|--|
| 0 | Support Bluetooth transceiver (BLE) On/Off mode |
| | Is "true" if the integrated BLE is running on Bluetooth-SW version 2.17 or higher. |
| 1 | BLE mode Off is permanent |
| | Is "false" since the BLE can be enabled via VE.Direct |

Available since version 1.17 for Smart Inverters

This register should only be accessed for reading. The write property is enabled for internal purposes only.

2.3 Generic device status registers

Status registers about the current mode of operation of the device

| ID | Register name | R/W | Туре | Scale | Unit | Note |
|--------|----------------------------|-----|------|-------|------|------|
| 0x0201 | VE_REG_DEVICE_STATE | R | un8 | - | - | |
| 0x0207 | VE_REG_DEVICE_OFF_REASON_2 | R | un32 | - | - | 1) |
| 0x031C | VE_REG_WARNING_REASON | R | un16 | - | - | |
| 0x031E | VE_REG_ALARM_REASON | R | un16 | - | - | |

Note 1) Since version 1.17. To receive announcements of this register via Bluetooth BLE-SW version 2.20 or higher is required.

2.3.1 Device state values (register 0x0201)

| State | Name | Meaning |
|-------|-----------|---|
| 0 | Off | Not inverting. When due to a protection the inverter will automatically start again when the cause is solved. |
| 1 | Low Power | Eco load search active |
| 2 | Fault | Not inverting due to a fatal active protection. A turn OFF-ON cycle is required to enable the device again. |
| 9 | Inverting | Normal operating |

2.3.2 Device off reasons (register 0x0207)

Each bit represents an off reason

| Bit | Meaning (bitN = 1: active, bitN = 0: inactive) |
|-----|---|
| 0 | No input power (will also cause a battery alarm) |
| 2 | Soft power button or SW controlled (VE.Direct or Bluetooth) |
| 3 | HW remote input connector |
| 4 | Internal reason (see alarm reason for more info) |
| 5 | PayGo, out of credit, need token |

2.3.3 Warning reasons (register 0x031C)

Each bit represents a warning or alarm reason.

| Bit | Meaning (bitN = 1: active, bitN = 0: inactive) |
|-----|---|
| 0 | Low battery voltage |
| 1 | High battery voltage |
| 5 | Low temperature |
| 6 | High temperature |
| 8 | Overload |
| 9 | Poor DC connection, triggered by battery current ripple or a hot DC terminal 1) |
| 10 | Low AC-output voltage |
| 11 | High AC-output voltage |

Note 1: DC terminal temperature measurement only available in the larger models

Note 2: A "High AC-output voltage" alarm occurs when the AC-output of the inverter is connected to mains while the inverter is turned on.

2.3.4 Alarm reasons (register 0x031E)

See §2.3.3 Warning reasons (register 0x031C) . But only the reason that triggered an alarm, causing the inverting to switch off to protect itself or the load, is shown.

2.4 Generic device control registers

Registers to control the mode of operation of the device

| ID | Register name | R/W | Туре | Scale | Unit | Note |
|--------|-------------------------|-----|------|-------|------|------|
| 0x0090 | VE_REG_BLE_MODE | R/W | un8 | - | - | 2) |
| 0x0200 | VE_REG_DEVICE_MODE | R/W | un8 | - | - | |
| 0xEC41 | VE_REG_SETTINGS_CHANGED | R/W | un32 | | | 3) |

Note 2) Since version 1.17. Smart-Inverters only, see §2.2.4 Capabilities (register 0x0140).

Note 3) Since version 1.17. Time in Unix-timestamp format. Default = 0xFFFFFFF. External applications can read and write to this register. It is not controlled by and has no effect on the operation of the inverter.

2.4.1 BLE mode (register 0x0090)

| State | Name | Meaning |
|-------|-------------|-------------------------|
| 0 | BLE-enabled | 0 = BLE off, 1 = BLE on |

Since version 1.17, see §2.2.4 Capabilities (register 0x0140)

Set 0 to disable the Bluetooth transceiver (BLE) of the Smart Inverters. When it is disabled it can be enabled via VE.Direct only.

2.4.2 Device mode values (register 0x0200, user setting)

| Mode | Meaning | Note |
|------|-----------------------------|----------------------------|
| 2 | Inverter On | |
| 3 | Device On (multi compliant) | 1) |
| 4 | Device Off | VE.Direct is still enabled |
| 5 | Eco mode | |
| 0xFD | Hibernate | VE.Direct is affected 2) |

Note 1) Available since version 1.15

Multi compliant value 1(Device On), the response value will be 2 (Inverter On)

Note 2) Available since version 1.15, see §2.2.4 Capabilities (register 0x0140). The Hibernate mode has impact on the VE.Direct functionality. Communication can only be started when the device sends a text frame, at least once per 30 seconds, or after pressing the User-button. As long as a VE.Direct message is received every 24 seconds the device will not enter the hibernation mode.(Note that communication via Bluetooth is not affected)

2.5 Inverter operation registers

Read only registers with measured information about the device

| ID | Register name | R/W | Type | Scale | Unit | Note |
|--------|------------------------------|-----|------|-------|------|------|
| 0x1040 | VE_REG_HISTORY_TIME | R | un32 | 1 | S | 1) |
| 0x1041 | VE_REG_HISTORY_ENERGY | R | un32 | 0.01 | kVAh | 1) |
| 0x2201 | VE_REG_AC_OUT_CURRENT | R | sn16 | 0.1 | А | |
| 0x2200 | VE_REG_AC_OUT_VOLTAGE | R | sn16 | 0.01 | V | |
| 0x2205 | VE_REG_AC_OUT_APPARENT_POWER | R | sn32 | 1 | VA | 2) |
| 0xEB4E | VE_REG_INV_LOOP_GET_IINV | R | sn16 | 0.001 | Α | |
| 0xED8D | VE_REG_DC_CHANNEL1_VOLTAGE | R | sn16 | 0.01 | V | |
| | (battery voltage) | | | | | |

Note 1) Since version 1.17, lifetime data

Note 2) Since version 1.15, see §2.2.4 Capabilities (register 0x0140)

2.6 User AC-out control registers

| ID | Register name | R/W | Туре | Scale | Unit | |
|--------|---|-----|------|-------|------|----|
| 0x0230 | VE_REG_AC_OUT_VOLTAGE_SETPOINT | W | un16 | 0.01 | V | |
| 0x0231 | VE_REG_AC_OUT_VOLTAGE_SETPOINT_MIN | R | un16 | 0.01 | V | 1) |
| 0x0232 | VE_REG_AC_OUT_VOLTAGE_SETPOINT_MAX | R | un16 | 0.01 | V | 1) |
| 0x2206 | VE_REG_AC_LOAD_SENSE_POWER_THRESHOLD | W | un16 | 1 | VA | 5) |
| 0x2207 | VE_REG_AC_LOAD_SENSE_POWER_CLEAR | W | un16 | 1 | VA | 5) |
| 0xEB03 | VE_REG_INV_WAVE_SET50HZ_NOT60HZ | W | un8 | | | |
| 0xEB04 | VE_REG_INV_OPER_ECO_MODE_INV_MIN | W | sn16 | 0.001 | Α | 2) |
| 0xEB06 | VE_REG_INV_OPER_ECO_MODE_RETRY_TIME | W | un8 | 0.25 | S | 3) |
| 0xEB10 | VE_REG_INV_OPER_ECO_LOAD_DETECT_PERIODS | W | un8 | 0.02/ | S | 4) |
| | | | | 0.016 | | |

Note 1) Limits for user setting VE_REG_AC_OUT_VOLTAGE_SETPOINT. Out of range input levels will be clamped to these levels.

Note 2) Eco search mode threshold based on AC-current (only for version 1.00 up to 1.14, see note 5)

Note 3) Interval of the power test bursts when the Eco load search mode is active.

Note 4) Since version 1.17. Duration of a power test burst, when Eco load search mode is active, expressed in number of periods of the AC-out frequency (either 50 or 60Hz). For some loads with a delayed "turn-on" response, like dimmable LED-lightbulbs, it is required to enlarge the default value in order to detect the load.

Note 5) Since version 1.15, see Capabilities in §2.2.4 Capabilities (register 0x0140). Eco search mode threshold with hysteresis based on apparent power. Replaces VE_REG_INV_OPER_ECO_MODE_INV_MIN. Available in Smart Inverters and in all VE-Direct inverters with a product revision >= 7 (see *Product Revision (register 0x0101))*

2.6.1 Load sense power hysteresis (register 0x2206 0x2207)

| user setting DEVICE_MODE | Connected load (and no active protections) | Eco load search mode |
|--------------------------|---|-------------------------|
| Eco | Load < VE_REG_AC_LOAD_SENSE_POWER_THRESHOLD | active |
| Eco | Load > VE_REG_AC_LOAD_SENSE_POWER_CLEAR | inactive |
| On | don't care | inactive |

Note: Typically, set the CLEAR level higher than the search activate THRESHOLD to prevent continues switching of the eco load search mode. The required minimal difference is load/inrush-current dependent.

2.6.2 AC out frequency (register 0xEB03)

| State | Name | Description |
|-------|------|--------------------------|
| 0 | 60Hz | AC-out frequency is 60Hz |
| 1 | 50Hz | AC-out frequency is 50Hz |

Changing this setting is only effective after the NvmSave command is executed, see §2.1

2.7 User battery control registers

| ID | Register name | R/ W | Туре | Scale | Unit | |
|--------|--|---------|------|-------|------|----|
| 0x2210 | VE_REG_SHUTDOWN_LOW_VOLTAGE_SET | W | un16 | 0.01 | V | 1) |
| 0x0320 | VE_REG_ALARM_LOW_VOLTAGE_SET | W | un16 | 0.01 | V | 2) |
| 0x0321 | VE_REG_ALARM_LOW_VOLTAGE_CLEAR | W | un16 | 0.01 | V | 3) |
| 0x2211 | VE_REG_VOLTAGE_RANGE_MIN | R | un16 | 0.01 | V | 4) |
| 0x2212 | VE_REG_VOLTAGE_RANGE_MAX | R | un16 | 0.01 | V | 4) |
| OxEBBA | VE_REG_INV_PROT_UBAT_DYN_CUTOFF_ENABLE | W | un8 | | | 5) |
| 0xEBB7 | VE_REG_INV_PROT_UBAT_DYN_CUTOFF_FACTOR | W | un16 | | | 5) |
| 0xEBB5 | VE_REG_INV_PROT_UBAT_DYN_CUTOFF_FACTOR2000 | W | un16 | | | 5) |
| 0xEBB3 | VE_REG_INV_PROT_UBAT_DYN_CUTOFF_FACTOR250 | W | un16 | | | 5) |
| 0xEBB2 | VE_REG_INV_PROT_UBAT_DYN_CUTOFF_FACTOR5 | W | un16 | | | 5) |
| 0xEBB1 | VE_REG_INV_PROT_UBAT_DYN_CUTOFF_VOLTAGE | R | un16 | 0.001 | V | 5) |

Note 1) Low battery voltage shutdown threshold.

Note 2) Low battery warning threshold, also below this level the inverter will not start-up after a shutdown.

Note 3) Charge detect threshold after a long-term low voltage shut down. If the battery voltage exceeds this level the alarm is cleared, and the inverter will restart.

Note 4) Limits for all battery user threshold settings, e.g. VE_REG_ALARM_LOW_VOLTAGE_SET. Out of range input levels will be clamped to these levels.

Note 5) Since version 1.03.

2.7.1 Dynamic cut-off enable (register 0xEBBA)

| State | Name | Meaning |
|-------|----------|--|
| 0 | Disabled | Shut down threshold is defined by |
| | | VE_REG_SHUTDOWN_LOW_VOLTAGE_SET |
| 1 | Enabled | Shut down threshold is a function of the AC-out current. |
| | | The effective level can be obtained via register |
| | | VE_REG_INV_PROT_UBAT_DYN_CUTOFF_VOLTAGE |

The dynamic cut off feature overrules the settings

VE_REG_SHUTDOWN_LOW_VOLTAGE_SET and

VE_REG_ALARM_LOW_VOLTAGE_SET.

The actual shutdown threshold is a function of the load current and can be obtained via register VE_REG_INV_PROT_UBAT_DYN_CUTOFF_VOLTAGE

2.8 Relay control registers

| ID | Register name | R/W | Туре | Scale | Unit | Note |
|--------|----------------------|-----|------|-------|------|------|
| 0x034E | VE_REG_RELAY_CONTROL | R/W | un8 | | | 1) |
| 0x034F | VE_REG_RELAY_MODE | W | un8 | | | 1) |

Note 1) Since version 1.15, see §2.2.4 Capabilities (register 0x0140)

2.8.1 Relay mode (register 0x034F) user setting

| State | Name | Meaning |
|-------|---------------------|--|
| 4 | Normal operation | Default, On during normal operation (warnings are ignored) |
| 0 | Warnings and alarms | Off when a warning or alarm is active (inverter on) |
| 5 | Battery low | Off when a low battery warning or alarm is active |
| 6 | External fan | On when the internal fan is on |
| 3 | Disabled relay | Always Off |
| 2 | Remote | Controlled by writing to VE_REG_RELAY_CONTROL (0x034E) |

2.8.2 Relay control or status (register 0x034E)

| State | Name | Meaning |
|-------|------|------------------------|
| 0 | Off | NO = open, NC = closed |
| 1 | On | NO = closed, NC = open |

The read response of this register is always is the current status of the relay. Only when the Relay mode is "Remote" the relays is controlled by writing 0 or 1 to this register. In other Relay modes writing to this register is ignored.

Revision Log

1) 2018-05-24

Initial document

2) 2018-9-13

Replaced "device id" with "product id"

3) 2018-11-22

Added changes for Smart Inverters supported since FW version 1.15

4) 2019-09-27

Added instructions on saving settings
Added 50Hz/60Hz setting
Added new features since FW version 1.17
Support Bluetooth on/off
Enhanced ECO load search mode timing

5) 2021-09-06

Add Product-ID for 5000VA Smart Inverters
Added description CAPABILITIES1 bit 27
Fix type of 0xEBBA 'VE_REG_INV_PROT_UBAT_DYN_CUTOFF_ENABLE' is un8